

Computational modelling of rhythm as alternation, iteration and hierarchy

Dafydd Gibbon

Universität Bielefeld

gibbon@spectrum.uni-bielefeld.de

ABSTRACT

Recently interest in rhythm has revived and a number of new empirical measures have been proposed, for example by Low and Grabe, and Ramus. Closer examination shows these models to be incomplete, however, with respect to both empirical and formal adequacy conditions. The present contribution addresses these issues in relation to hierarchical temporal structuring and proposes an integrated computational phonetic approach, introducing an empirical data mining heuristic for inducing rhythm timing trees from large quantities of time-annotated data. New algorithms are proposed for Timing Tree Induction (TTI), and for a Tree Similarity Index (TSI) to estimate the similarity between syntax parse trees and prosodic trees as predictors for the structure of the temporal TTI trees. A preliminary quantitative evaluation shows a preference for tail-heavy (iambic) tree branching in a read-aloud narrative. Applications in speech genre analysis and for duration modelling in speech synthesis are envisaged.

1 INTRODUCTION

A number of new quantitative models of rhythm timing have been advanced in recent years, and used to compare different languages [1, 2]. The present contribution aims to examine the adequacy of these models, on the basis of the results to propose and test a method for automatically inducing rhythm timing trees from annotated data, and to evaluate grammatical structures as predictors for these timing trees. The computational phonetic methodology is new, and consequently “clear case” data from a read-aloud narrative are used for this initial study.¹ Results for more spontaneous spoken genres will presumably be less clear-cut.

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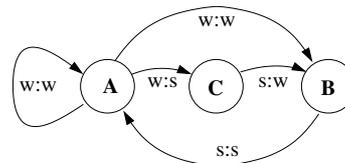


Figure 1: Basic rhythm filter FST (A, B are both initial and final nodes.)

2 RHYTHM TIMING MODELS

Current models of rhythm timing in speech are quite diverse but at the same time atomistic and selective, in that they focus on single parameters as different as global deviation of unit length, local unit length ratios, and consonant-vowel ratios [3, 1, 2], but do not cover non-binary rhythms or hierarchical factors in rhythm timing. More comprehensive approaches are emerging, however [4, 5, 6].

The dynamics of rhythm patterns include iteration (oscillation, from an operational perspective), and subordination to hierarchical timing patterns. The iterative component relates to Finite State (FS) phonology and prosody [7, 8, 4]. Both dimensions of hierarchical and iterative structure are found in Metrical Phonology [9, 10]. The hierarchical constraints are derived from grammatical structures, their core being the Nuclear Stress Rule (NSR). The earliest versions of the NSR were inner-bracket-removing operations on character strings containing well-formed nested bracketings. Liberman & Prince developed a tree-graph algorithm: a node-labelled binary tree has r on the root node, s on right daughter nodes, w on the others, and leaves are assigned abstract stress values equal to the depth of the first non- s node above the leaf. But the NSR is basically a recursive function:

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nsr(t,n,m) { if (leaf? (t))
              then make-group(make-label(t,m))
              else concat(nsr(first(t),n+1,n+1),
                          nsr(rest(t),n+1,m)) }
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Linear alternation constraints are expressed as

histogram-like grids. Such constraints may be implemented Finite State Transducer (FST) filters, shown in the example in Figure 1, a filter with oscillatory loops which enforces the so-called Rhythm Rule (cf. *THIRTEEN MEN* but *thirTEEN*) and avoids metrical clashes. This FST applies to whatever phonostylistically determined “zoom” level of structural granularity is needed (syllable, foot, or larger unit) [11].

Roughly speaking, phonological models of rhythm have concentrated on the hierarchical component, while phonetic approaches have concentrated on the iterative component.

A classic phonetic approach to rhythm timing is that of Roach [3]: tone unit duration is divided by the number of feet in the tone unit, yielding average or “ideal” foot duration approximating to isochrony, and the normalised deviation from mean foot length is measured. The idea, of course, is to measure *syllable isochrony*, rather than rhythm as such. Neither hierarchy nor linear alternation of timing units figure in the approach, which may be said to use a *Global Evenness* (GE) criterion as a measure of the isochrony property, rather than the alternation property. Any arbitrary resorting of the relevant segments in an utterance (random, shortest-to-longest, etc.) would yield the same index. Rhythm timing fulfils the GE criterion, in some sense, but it has other properties too, so while the GE criterion for timing is a necessary criterion for rhythm, it is not a sufficient one.

Ramus, Nespor & Mehler [2] locate different languages in a typologically distinctive timing space over the following parameters: $V\%$, percentage of V (vocalic intervals) relative to overall utterance length; ΔC , variance of consonantal intervals; ΔV , variance of vocalic intervals. The $V\%$ measure reflects preferences for certain phonotactic patterns (CV, CVC, vowel length) as corpus tokens rather than lexical types. The model also uses a variety of GE criterion: V stretches and C stretches would still yield the same results if randomly sorted (by length, longer consonant sequences first, etc.). Similar considerations apply to the ΔV measure, which reflects evenness of vowel sequence lengths, lower values tending to isochrony, and to the ΔC measure. The model does not have hierarchical and alternating timing components and is thus incomplete as a model of rhythm timing. Perhaps a different measure, such as ΔCV , could be used to address the issues of hierarchical and iterative structuring. A perceptual control for rhythmicity is clearly needed. As Cummins has pointed out [5], the measure makes a statement about the evenness of the phonotactics of the language, rather than rhythm, rather like Roach’s model; it reflects a possibly necessary condition on rhythm, but falls short of providing a sufficient condition.

Low, Grabe & Nolan [1] addressed the GE issue and developed the Pairwise Variability Index (PVI)

in order to take iterative alternation into account. The PVI measures normalised differences between the durations of adjacent units (vowels, syllables, etc.):

$$PVI = 100 \times \sum_{k=1}^{m-1} \left| \frac{d_k - d_{k+1}}{(d_k + d_{k+1})/2} \right| / (m - 1)$$

Wetzel’s [12] comment that the PVI factors out final lengthening is mistaken: the counter does not stop short of the final item — a sequence of length m just has $m - 1$ differences between neighbours. The model yields a minimal value of 0 (perfect isochrony), asymptotically approaching 200 for larger length differences; the variant used in [13] reverses the scale, and has a maximum of 100 for perfect isochrony. The model has an empirical problem: it assumes *strictly binary rhythm*. Hence, alternations as in “*Little John met Robin Hood and so the merrie men were born.*” are adequately modelled, but not the unary rhythm (syllable timing) of “*This one big fat bear swam fast near Jane’s boat.*” or ternary dactylic and anapaestic rhythms (or those with even higher cardinality) like “*Jonathan Appleby wandered around with a tune on his lips and saw Jennifer Middleton playing a xylophone down on the market-place.*” But the model unfortunately also has a formal problem: the PVI yields the same value for sets of alternating patterns and monotonic geometrical series, and for mixes of these ($n!$ patterns with identical PVI for series of a length n). It is easily verified that alternating sequences may receive the same PVI as exponentially increasing or decreasing series $PVI(2, 4, 2, 4, 2, 4) = PVI(2, 4, 8, 16, 32, 64)$. This is obviously not the desired result. Interesting though the resulting typological patterns are, it is not at all clear what they are patterns of. This model, too, is empirically and formally incomplete.

Cummins [5] discusses a number of additional factors involved in the production of rhythm in different styles, ranging from a paradigm of synchronous speaking designed to elicit maximally rhythmic utterances, to less constrained styles. He addresses both hierarchical and linear factors, and proposes a model for the more constrained styles with binary hierarchical structure, i.e. groupings of two-word feet, higher level groupings of two feet with four words, and so on. A new aspect of Cummins’ experimental approach is the emphasis on the entrainment of different factors in the synchronous production of rhythm, particularly the interaction of discrete and gradient factors, with coupling between prosodic factors at foot level and a higher level.

Wagner [4] criticises the hierarchical NSR type approach of Metrical Phonology (without rejecting a grid filter component, however), and concentrates on the linear alternation criterion, using FSTs with local cycles to formalise metrical grid type linear filters. Wagner shows that better results for synthesis of German speech are given by a linear model based on five part-of-speech sets with different intrinsic weighted abstract stress values [4]: {Nouns, Numerals, Proper Names},

Syntax–Timing Tree Correspondences

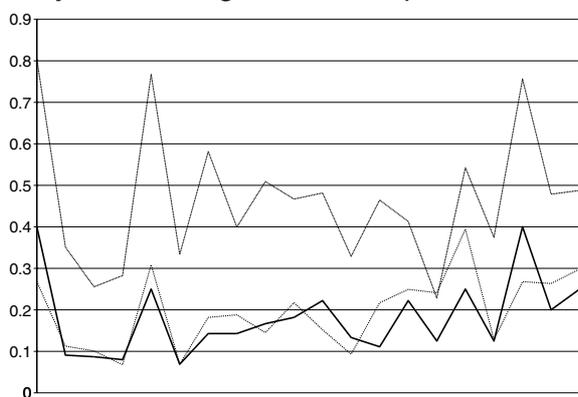


Figure 4: Syntax-prosody correspondences in read-aloud narrative (X: syntax/TTI tree pairs, Y: TSI).

trees and unparsed (UP) sentences, the higher thin line shows mean TSI for TTI-A short-long (iambic) grouped trees, the lower thin line shows mean TSI for TTI-B long-short (trochaic) grouped trees. Both TTI-A (0.85) and TTI-B (0.89) TSI sequences correlate highly with the UP sequence, probably due to shallow bracketing, but the TSI levels differ considerably. Averaged over all subjects and sentences: TTI-A mean TSI = 0.47; TTI-B mean TSI = 0.2; UP condition: mean TSI = 0.19. Clearly, mean TSI for A (short-long) is much higher than for B (long-short) or UP, which are indistinguishable. Syntax and TTI trees are thus more similar under TTI-A than under TTI-B. The methodological orientation of the study and the number of subjects do not currently justify further statistical evaluation.

5 TOWARD AN INTEGRATED RHYTHM TIMING MODEL

The visualisation shows a preference for a *match between grammatical structures and iambic groups*, with short-long constituent pairs. An interesting result: the structure is like the end-weighted (iambic) Nuclear Stress Rule, not the trochaic structures often proposed for English rhythm. A number of points remain open: generalisation to other speech genres, deeper bracketing, normalisation for sentence length effects, use of a broader selection of subjects, statistical treatment. This research programme is facilitated by the non-language-specific TTI and TSI algorithms, and an implementation for arbitrary time-annotated data.

Nevertheless, the results are encouraging, and suggest that TTI and TSI could form the core of a prosodic data mining strategy for utilising the enormous quantities of annotated speech resources amassed in Eu-

ropean and national projects, for instance in training hierarchical duration models for speech synthesis.

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