

An Operational and Denotational Approach to Non-Context-Freeness

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Abstract

The main result of this paper is a description of linguistically motivated non-context-free phenomena equivalently in terms of regular tree languages (to express the recursive properties) and both a logical and an operational perspective (to establish the intended linguistic relations). The result is exemplified with a particular non-context-free phenomenon, namely cross-serial dependencies in natural languages such as Swiss German or Dutch. The logical description is specified in terms of binary monadic second-order (MSO) formulas and the operational description is achieved by means of a linear and non-deleting macro tree transducer. Besides giving a grammatical presentation for the regular tree language we shall also specify an implementation in the form of a finite-state (tree) automaton to emphasize the effectivity of our approach.

Key words: Tree Grammars, MSO logic, non-context-free phenomena

1 Introduction

There are many kinds of structural phenomena in natural languages that cannot be captured by context-free string grammars or regular tree grammars

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(RTGs). Among these phenomena cross-serial dependencies have played a prominent rôle in the discussions about the right level of complexity to be assumed for a descriptively adequate linguistic theory. In order to concentrate on the relevant details, we will use in this paper a corresponding artificial example exemplifying the linguistic construction to illustrate our proposal.

The main results of this paper are twofold. The first one is a description of cross-serial dependencies in terms of regular tree languages (to express the recursive properties) and a special type of tree transformation effected by a linear non-deleting macro tree transducer (MTT). Besides giving a grammatical presentation for the regular tree language we shall also create an implementation in the form of a finite-state (tree) automaton to emphasize the effectivity of our approach.

The other result is a logical description of cross-serial dependencies in terms of monadic second-order (MSO) logic. The description says that the structures underlying crossing dependencies can be specified as MSO definable relations. These have to be defined on a domain of finite trees which is characterized as the model set of a (closed) MSO formula.

For regular string and tree languages, classical results in the descriptive theory of recognizability have established a tight connection between logical formalisms and language classes. They provide translation procedures that transform logical specifications into finite automata equivalent to the language classes and vice versa. Büchi (1960) and Elgot (1961) have shown that regular string languages represented through finite (string) automata can be expressed by sentences in the weak MSO logic with one successor. For tree languages an analogous result is well known: a tree language is definable in weak MSO logic with multiple successors if and only if it is recognizable by a finite tree automaton (Doner, 1970; Thatcher and Wright, 1968).

It is these earlier characterizations that provide the reason for a renewed interest in logical approaches to grammar specifications. The main open question in this area of research is whether an appropriate extension of the MSO language can be found which is expressive enough to define significant properties of natural languages without becoming too unwieldy from the perspective of complexity theory.

The logical approach to the specification of language classes involves a lot of advantageous properties that have paved the way to its application to linguistic issues. First, the equivalence between automata theoretic operational and logic oriented declarative formalisms leads to a lot of closure properties of the defined language classes. The properties follow immediately from the closure of the specification logics with respect to the classical operations like negation, conjunction, alternation and (universal and existential) quantifica-

tion. Second, the transition from strings to finite model-theoretic structures of arbitrary signatures requires no extra conceptual or technical ideas in the logical framework whereas in formal language theory the step from string to tree languages and the concomitant distinction between weak and strong generative capacity constitutes a significant extension of the research agenda. Third, since the logical approach does not depend on an operational process, its statements can be phrased in terms of linguistically significant notions that enter into universal principles and language-particular constraints. This is due to the fact that an operational process starts from some given objects and then generates its space of interpretation. The logical approach, on the other hand, refers directly to an assumed universe of structures. Finally, those logical languages that capture complexity classes indicate lower bounds on the computing resources a system has to make available for using those structures that fall within the classes correlated with the corresponding logical language (Immerman, 1987).

In a previous paper (Kolb et al., 2000) we have shown how to implement the binary MSO formulas mentioned above by finite-state tree-walking automata. In this paper we show that the intended linguistic structures can be regained by a simple MTT. To be more precise, we construct, in a first step, a regular representation of the cross-serial dependencies using a certain amount of explicit control information. Trees exhibiting this control information are elements of an absolutely free algebra on a signature that results from a well-known derivation process to be explained further below. The MTT serves to evaluate the tree terms of the free algebra in a different semantic domain. In other words, it constitutes the implementation of the uniquely given homomorphism which sends the trees with the explicit control information into the originally intended structures.

MTTs integrate the top-down aspect of a tree transducer and the bottom-up aspect of a context-free tree grammar (CFTG). The formalism of CFTGs was introduced by Fischer (1968) and constitutes a generalization of RTGs. Recall that the step from regular to context-free string grammars essentially consists in lifting the restriction to initial and final string positions for nodes to be substitutable. In analogy, the rule format which characterizes CFTGs allows for the substitution of inner tree nodes in contrast to RTGs which limit substitutability to terminal nodes. According to the analysis above, a CFTG appears as an MTT without any input. Our MTT receives its input information from the lifted trees exhibiting the control information and handles its context information via the arguments of its states. These context parameters play the same rôle as the parameters in the original CFTG. Since the tree-walking automata that served to give an operational account of the intended linguistic relations in Kolb et al. (2000) had to be constructed on a piecemeal basis, the question remained open of how to specify an implementation in a more compact way. We hope that the present result gives a satisfying answer

to this question.

The structure of the paper is as follows. After some technical preliminaries we outline a grammatical representation of a particular example of cross-serial dependencies, the verbal complex in Swiss German and Dutch, within the formalism of CFTGs. After this first step we LIFT the generated trees by inserting a certain amount of explicit control information. It turns out that the resulting structures can be characterized with RTGs. We exploit the equivalence of RTGs/tree automata and MSO specifications in constructing a closed formula that cuts out of the universal realm of all possible finite trees on the explicit signature just those elements that have counterparts in the original context-free tree family. The final step simulates the structural relations of the original trees. These structural relations turn out to be definable by MSO formulas that are defined on the nodes of the lifted trees. The actual formal definition will take the form of an MSO definable transduction translating the lifted structures into the intended ones. We supplement this logical simulation with an operational account of this logic based transduction. As was outlined in the preceding paragraph, we provide the necessary details of an MTT that performs in a clearly operational way the sort of tree transformation that is—statically—specified by the MSO transduction.

The basic idea underlying this sequential application of two logical specification steps can be found in the signature free treatment of universal algebra that was developed in the early 60s. According to this treatment, the most important rôle in an algebra is played by the set of all operations definable from the primitive ones by composition and not by the primitive operations themselves. These defined operations then constitute the carrier of a (multi-sorted) algebra whose only non-unary operations are provided by suitably sorted instances of composition.

Strings (in concatenation algebras) and trees (in term algebras) are the appropriate ranges for the variables in context-free string and regular tree grammars, respectively. In the same way, defined tree operations are the appropriate range for variables in CFTGs. In the case of strings and trees the process of substituting an element of the carrier of these algebras for a variable involves a simple process of insertion. In the case of defined operations the original arguments of the replaced (multi-ary) variable have to be composed with its substitute. Once these two components of the process of higher-order substitution are pulled apart we are free to formally indicate them by means of separate notational ingredients: the variable substituent on the one hand and the composition operator on the other. Thereby we arrive at the notion of a lifted free algebra.

Since the variables in the context of a lifted free algebra are separated from their arguments, the process of substituting an appropriate multi-ary defined

operation for them takes the form of leaf substitution familiar from RTGs. It was Maibaum (1974) who first adapted the treatment of universal algebra developed in category theory to the context of formal language theory. The topic was taken up again in Engelfriet and Schmidt (1977; 1978), who also give an account of the influence of different modes of derivation, an issue that was not correctly stated in Maibaum's presentation. The fact that derivation steps on the original and the lifted structural level are in one-one correspondence is proved in Mönnich (1999).

A result similar in spirit to the one established in this paper can be found in Engelfriet and van Oostrom (1996). They show that context-free graph languages have a regular path description. Given the context of graph theory the authors use for their first step a regular family of derivation trees and formalize the effect of connection instructions in terms of suitable node labels in the derivation trees.

Similarly, in Courcelle (1992), a certain type of context-free graph languages is characterized as an equational subset of an algebra over a binary glueing operation and a family of definable unary operations. In contrast to the approach favored by Courcelle, we do not evaluate these operations, but interpret the intended linguistic relations directly on the structures given as elements of the free term algebra.

We think that the logical part of our approach has two decisive advantages. First, the operations of the relevant signature appear explicitly in the lifted trees and are not hidden in node labels coding instances of rule application. Second, our binary MSO formulas are not dependent on the particular regular tree family or the domain defined via the MSO formula. The instruction set of the tree-walking automata behind these formulas and the corresponding definition of the MSO transduction are universal and only serve to reverse the lifting process. In that sense the instructions are nothing else but a restatement of the unique homomorphism which exists between the free algebra and any other algebra of the same signature. The same statement holds for the MTT. Its rules serve to evaluate the instructions implicit in the composition and projection symbols. These instructions are again independent of the particular tree family specified by the closed MSO formula.

2 Preliminaries

The purpose of this section is to fix notations and to present definitions for the basic notions related to tree grammars, the classes of automata and MSO logic which will be used in the paper. We have taken pains to give a full list of definitions to make the paper as self-contained as possible.

2.1 Universal Algebra

Throughout the paper the following conventions apply. \mathbb{N} is the set of all non-negative integers. For any set M , M^* is the Kleene closure of M , i.e., the set of all finite strings over M . For $m \in M^*$, $|m| \in \mathbb{N}$ denotes the length of m . We will use ε to denote the empty string (over M), i.e., $\varepsilon \in M^*$ with $|\varepsilon| = 0$.

Definition 1 For a given set of sorts \mathcal{S} , a *many-sorted signature (over \mathcal{S})*, Σ , is an indexed family $\langle \Sigma_{w,s} \mid w \in \mathcal{S}^*, s \in \mathcal{S} \rangle$ of disjoint sets. A symbol $\sigma \in \Sigma_{w,s}$ is an *operator of type $\langle w, s \rangle$, arity w , sort s and rank $|w|$* . The rank of σ is denoted by $\text{rank}(\sigma)$.

The *set of trees or terms (over Σ)*, $T(\Sigma)$, is built up using the operators in the usual way: If $\sigma \in \Sigma_{\varepsilon,s}$ for some $s \in \mathcal{S}$ then σ is a (trivial) tree of sort s . If, for some $s \in \mathcal{S}$ and $w = s_1 \cdots s_n$ with $s_i \in \mathcal{S}$, $\sigma \in \Sigma_{w,s}$ and $t_1, \dots, t_n \in T(\Sigma)$ with t_i of sort s_i then $\sigma(t_1, \dots, t_n)$ is a tree of sort s .

In case \mathcal{S} is a singleton $\{s\}$, i.e., in case Σ is a *single-sorted signature (over sort s)*, we usually write Σ_n to denote the (unique) set of operators of rank $n \in \mathbb{N}$,¹ and we refer to Σ simply as a *ranked alphabet*.

The operator symbols of a many-sorted signature Σ over some set of sorts \mathcal{S} induce operations on an algebra with the appropriate structure. A Σ -*algebra* \mathbb{A} consists of an \mathcal{S} -indexed family $A = \langle A_s \mid s \in \mathcal{S} \rangle$ of disjoint sets, the carriers of \mathbb{A} , and for each operator $\sigma \in \Sigma_{w,s}$, $\sigma_{\mathbb{A}} : A_w \rightarrow A_s$ is a function, where $A_w = A^{s_1} \times \cdots \times A^{s_n}$ and $w = s_1 \cdots s_n$ with $s_i \in \mathcal{S}$. The set $T(\Sigma)$ can be made into a Σ -algebra $\mathbb{T}(\Sigma)$ by specifying the operations as follows. For every $\sigma \in \Sigma_{w,s}$, where $s \in \mathcal{S}$ and $w = s_1 \cdots s_n$ with $s_i \in \mathcal{S}$, and every $t_1, \dots, t_n \in T(\Sigma)$ with t_i of sort s_i we identify $\sigma_{\mathbb{T}(\Sigma)}(t_1, \dots, t_n)$ with $\sigma(t_1, \dots, t_n)$.

Different algebras, defined over the same operator domain, are related to each other if there exists a mapping between their carriers that is compatible with the basic structural operations. A Σ -*homomorphism* of two Σ -algebras $\mathbb{A} = \langle A, (\sigma_{\mathbb{A}})_{\sigma \in \Sigma} \rangle$ and $\mathbb{B} = \langle B, (\sigma_{\mathbb{B}})_{\sigma \in \Sigma} \rangle$ is a function h from A to B such that for every operator $\sigma \in \Sigma_{w,s}$ it holds that $h(\sigma_{\mathbb{A}}(a_1, \dots, a_{|w|})) = \sigma_{\mathbb{B}}(h(a_1), \dots, h(a_{|w|}))$ for every $|w|$ -tuple $\langle a_1, \dots, a_{|w|} \rangle \in A^w$, where $s \in \mathcal{S}$ and $w = s_1 \cdots s_n$ with $s_i \in \mathcal{S}$.

Every tree $t \in T(\Sigma)$ has a value in every Σ -algebra \mathbb{A} . It is the value at t of the unique homomorphism $h : \mathbb{T}(\Sigma) \rightarrow \mathbb{A}$.

¹ Note that for $\mathcal{S} = \{s\}$ each $\langle w, s \rangle \in \mathcal{S}^* \times \mathcal{S}$ is of the form $\langle s^n, s \rangle$ for some $n \in \mathbb{N}$, i.e., \mathcal{S}^* can be identified with \mathbb{N} , because up to length each $w \in \mathcal{S}^*$ is uniquely specified.

Let Σ be a ranked alphabet. For each set Y , $T(\Sigma, Y)$ is the set of trees $T(\Sigma(Y))$ over the ranked alphabet $\Sigma(Y) = \langle \Sigma(Y)_n \mid n \in \mathbb{N} \rangle$, where $\Sigma(Y)_0 = \Sigma_0 \cup Y$ and $\Sigma(Y)_n = \Sigma_n$ for $n > 0$. Furthermore, we take $\mathbb{T}(\Sigma, Y)$ to denote the Σ -algebra $\mathbb{A} = \langle A, (\sigma_{\mathbb{A}})_{\sigma \in \Sigma} \rangle$ with $A = \langle T(\Sigma, Y)^n \mid n \in \mathbb{N} \rangle$ and $\sigma_{\mathbb{A}} = \sigma_{\mathbb{T}(\Sigma)}$ for $\sigma \in \Sigma$.

Now, let $X = \{x_1, x_2, x_3, \dots\}$ be a countable set of variables, for $k \in \mathbb{N}$ define $X_k \subseteq X$ as $\{x_1, \dots, x_k\}$. Then, $T(\Sigma, X_k)$ is the set of k -ary trees (over Σ). The existence of a particular homomorphism from $\mathbb{T}(\Sigma, X_k)$ into an arbitrary Σ -algebra \mathbb{A} provides the basis for the view that regards the elements of $T(\Sigma, X_k)$ as *derived operations*: Each tree $t \in T(\Sigma, X_k)$ induces a k -ary function $t_{\mathbb{A}}$ from A^k to A . The meaning of $t_{\mathbb{A}}$ is defined such that for every k -tuple $\langle a_1, \dots, a_k \rangle \in A^k$, $t_{\mathbb{A}}(a_1, \dots, a_k) = \hat{a}(t)$, where \hat{a} is the unique homomorphism from $\mathbb{T}(\Sigma, X_k)$ to \mathbb{A} with $\hat{a}(x_i) = a_i$.

In the particular case where \mathbb{A} is the Σ -algebra $\mathbb{T}(\Sigma, X_l)$ for some $l \in \mathbb{N}$ the unique homomorphism extending the assignment of a tree $t_i \in T(\Sigma, X_l)$ to the variable x_i in X_k acts as a substitution $t_{\mathbb{T}(\Sigma, X_l)}(t_1, \dots, t_k) = t[t_1, \dots, t_k]$, where the right hand side indicates the result of substituting t_i for x_i in t .

2.2 Tree Grammars

We now formally introduce the notion of a context-free tree grammar (CFTG). This type of grammar is related to a type of grammars defined by Fischer (1968) and called *macro grammars*. In his setting, the use of macro-like productions served the purpose of making simultaneous string copying a primitive operation. CFTGs constitute an algebraic generalization of macro grammars (cf. Rounds 1970).

Let us view grammars as a mechanism in which local transformations on trees can be performed. The central ingredient of a grammar is a finite set of productions, where each production is a pair of trees. Such a set of productions determines a binary relation on trees such that two trees t and t' stand in that relation if t' is the result of removing in t an occurrence of a first component in a production pair and replacing it by the second component of the same pair. The simplest type of such a replacement is defined by a production that specifies the substitution of a single-node tree t_0 by another tree t_1 . Two trees t and t' satisfy the relation determined by this simple production if the tree t' differs from the tree t in having a subtree t_1 that is rooted at an occurrence of a leaf node t_0 in t . In slightly different terminology, productions of this kind incorporate instructions to rewrite auxiliary variables as a complex symbol that, autonomously, stands for an element of a tree algebra. Recall that in context-free string grammars a nonterminal auxiliary symbol is rewritten as a string of terminal and nonterminal symbols, independently of the context in

which it occurs. As long as the carrier of a tree algebra is made of constant tree terms the process of replacing null-ary variables by trees is analogous. As we will see, the situation changes dramatically if the carrier of the algebra is made of symbolic counterparts of derived operations and the variables in production rules range over these second-level entities.

Definition 2 (Context-Free Tree Grammar) For a singleton set of sorts \mathcal{S} , a *context-free tree grammar (CFTG)* for \mathcal{S} is a 5-tuple $\Gamma = \langle \Sigma, F, S, X, P \rangle$, where Σ and F are ranked alphabets of *inoperatives* and *operatives* over \mathcal{S} , respectively. $S \in F$ is the start symbol, X is a countable set of variables, and P is a set of productions. Each $p \in P$ is of the form $F(x_1, \dots, x_n) \rightarrow t$ for some $n \in \mathbb{N}$, where $F \in F_n$, $x_1, \dots, x_n \in X$, and $t \in T(\Sigma \cup F, \{x_1, \dots, x_n\})$.

An application of a rule $F(x_1, \dots, x_n) \rightarrow t$ “rewrites” a tree rooted in F as the tree t with its respective variables substituted by F ’s daughters.

A CFTG $\Gamma = \langle \Sigma, F, S, X, P \rangle$ with $F_n = \emptyset$ for $n \neq 0$ is called a *regular tree grammar (RTG)*. Since RTGs always just substitute some tree for a leaf-node, it is easy to see that they can only generate recognizable sets of trees, *a fortiori* context-free string languages (Mezei and Wright, 1967). If F_n is non-empty for some $n \neq 0$, that is, if we allow the *operatives* to be parameterized by variables, however, the situation changes. CFTGs in general are capable of generating sets of structures, the *yields* of which belong to the class of context-sensitive languages known as the *indexed* languages.

In fact, CFTGs characterize the class of indexed languages modulo the inside-out derivation mode (Rounds, 1970). For reasons having to do with the impossibility of mirroring the process of copying in a grammar with a completely uncontrolled derivation regime, we restrict ourselves this particular mode of derivation. Accordingly, a function symbol may be replaced only if all its arguments are trees over the terminal alphabet. In the conventional case this form of replacement mechanism would correspond to a “rightmost” derivation where “rightmost” is to be understood with respect to the linear order of the leaves forming the frontier of a tree in a derivation step.

Definition 3 Let $\Gamma = \langle \Sigma, F, S, X, P \rangle$ be a CFTG and let $t, t' \in T(\Sigma \cup F)$. t' is *directly derivable* by an *inside-out step* from t ($t \Longrightarrow t'$) if there is a tree $t_0 \in T(\Sigma \cup F, \{x_1\})$ containing exactly *one* occurrence of x_1 , a corresponding rule $F(x_1, \dots, x_m) \rightarrow t''$, and trees $t_1, \dots, t_m \in T(\Sigma)$ such that $t = t_0[F(t_1, \dots, t_m)]$ and $t' = t_0[t''[t_1, \dots, t_m]]$. By the inside-out restriction on the derivation scheme it is required that the trees t_1, t_2 through t_n be terminal trees, i.e., do not contain variables or operatives. As is customary \Longrightarrow^* denotes the transitive-reflexive closure of \Longrightarrow .

In the following definition of a tree language we now switch back to accepting

only trees over the ranked alphabet Σ , i.e., we do not allow operatives to remain in the final trees.

Definition 4 (Inside-Out Tree Language) Let $\Gamma = \langle \Sigma, F, S, X, P \rangle$ be a CFTG. We call $\mathcal{L}(G, S) = \{t \in T(\Sigma) \mid S \xrightarrow{*} t\}$ the *context-free inside-out tree language* generated by G from S .

In the case of RTGs the analogy with the conventional string theory goes through and inside-out and outside-in derivations yield the same languages.

We will exemplify the gain in generative power of context-free tree grammars compared to RTGs—or standard context-free grammars—with an artificial construction of the string language $a^n b^m c^n d^m$ which is a subset of the actual non context-free dependencies occurring in Swiss German (see Section 3). The example uses the full power of the second-order substitutions of derived operators.

$$\begin{array}{lll}
\Sigma_0 = \{\varepsilon, a, b, c, d\} & & \Sigma_2 = \{\bullet\} \\
X = \{x_1, x_2, x_3, x_4\} & F_0 = \{S\} & F_4 = \{F\}
\end{array}$$

$$P = \left\{ \begin{array}{l}
S \longrightarrow \varepsilon \\
S \longrightarrow F(a, \varepsilon, c, \varepsilon) \\
S \longrightarrow F(\varepsilon, b, \varepsilon, d) \\
F(x_1, x_2, x_3, x_4) \longrightarrow F(\bullet(a, x_1), x_2, \bullet(c, x_3), x_4) \\
F(x_1, x_2, x_3, x_4) \longrightarrow F(x_1, \bullet(b, x_2), x_3, \bullet(d, x_4)) \\
F(x_1, x_2, x_3, x_4) \longrightarrow \bullet(\bullet(\bullet(x_1, x_2), x_3), x_4)
\end{array} \right. \quad (1)$$

The tree language generated by the grammar in (1) can intuitively be described as a parallel derivation of a 's and c 's and b 's and d 's. Therefore, the number of occurrences of a 's and c 's and of b 's and d 's, respectively, has to be the same. By taking the yield of the tree terms, we get the language $\mathcal{L}' = \{a^n b^m c^n d^m\}$.

In Figure 1 we show an example derivation of the string $aabccd$. It uses the second rule for S , followed by successive application of the first, second and third rule for F .

The definition of a CFTG given above could be canonically generalized to the case of many-sorted signatures Σ and F over some set of sorts \mathcal{S} . Since we will be concerned with such generalized versions of CFTGs only in their regular form, we restrict our definition to simplify our presentation.

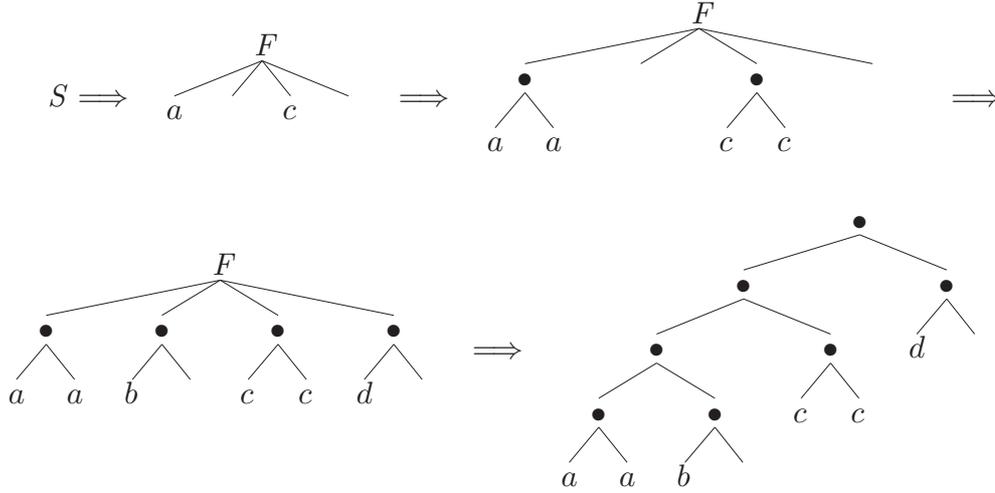


Fig. 1. An example derivation of (1): $aabccd$

Definition 5 (Regular Tree Grammar) For a set of sorts \mathcal{S} , a *regular tree grammar* (RTG) for \mathcal{S} is a 4-tuple $\mathcal{G} = \langle \Sigma, F, S, P \rangle$, where $\Sigma = \langle \Sigma_{w,s} \mid w \in \mathcal{S}^*, s \in \mathcal{S} \rangle$ is a many-sorted signature of *inoperatives* and $F = \langle F_{\varepsilon,s} \mid s \in \mathcal{S} \rangle$ a (reduced) many-sorted signature of *operatives* of rank 0. Moreover, Σ and F are finite. $S \in F$ is the start symbol and P is a finite set of productions. Each $p \in P$ has the form $F \rightarrow t$, where $F \in F_{\varepsilon,s}$ for some $s \in \mathcal{S}$ and $t \in T(\Sigma \cup F)$, i.e., a term (tree) over $\Sigma \cup F$, such that t is of sort s .

Let $t', t'' \in T(\Sigma \cup F)$ and $p = F \rightarrow t \in P$. t' *directly derives* t'' (by the application of p), also denoted by $t' \Rightarrow t''$, if t' has a leaf-node F and t'' results from t' by substituting this node F by t . Let \Rightarrow^* be the reflexive and transitive closure of \Rightarrow . The tree-language generated by \mathcal{G} is the set $L_T(\mathcal{G}) = \{t \in T(\Sigma) \mid S \Rightarrow^* t\}$.

Since RTG-rules based on a multi-sorted signature still always just substitute some tree for a leaf-node, it is still the case that they generate recognizable sets of trees, i.e., context-free string languages.

Any *context-free* tree grammar Γ for a singleton set of sorts \mathcal{S} can be transformed into a *regular* tree grammar Γ^L for the set of sorts \mathcal{S}^* , which characterizes a (necessarily recognizable) set of trees encoding the instructions necessary to convert them by means of a unique homomorphism h into the ones the original grammar generates (Maibaum, 1974). This “LIFTing” is achieved by constructing for a given single-sorted signature Σ a new, derived alphabet (an \mathbb{N} -sorted signature) Σ^L , and by translating the terms over the original signature into terms of the derived one via a primitive recursive procedure. The LIFT-operation takes a term in $T(\Sigma, X_k)$ and transforms it into one in $T(\Sigma^L, k)$. Note that since \mathcal{S} is a singleton, we can identify \mathcal{S}^* with \mathbb{N} (cf. fn. 1). Therefore we denote the set of all trees over Σ^L which are of sort k by $T(\Sigma^L, k)$. Intuitively, the lifting eliminates variables and composes functions

with their arguments explicitly, e.g., a term $f(a, b) = f(x_1, x_2) \circ (a, b)$ is lifted to the term $c(c(f, \pi_1, \pi_2), a, b)$.

Definition 6 (LIFT) Let Σ be a ranked alphabet and $X_k = \{x_1, \dots, x_k\}$, $k \in \mathbb{N}$, a finite set of variables. The *derived* \mathbb{N} -sorted alphabet Σ^L is defined as follows: For each $n \geq 0$, $\Sigma'_{\varepsilon, n} = \{f' \mid f \in \Sigma_n\}$ is a new set of symbols of type $\langle \varepsilon, n \rangle$; for each $n \geq 1$ and each $i, 1 \leq i \leq n$, π_i^n is a new symbol, the i th *projection symbol* of type $\langle \varepsilon, n \rangle$; for each $n, k \geq 0$ the new symbol $c_{n, k}$ is the (n, k) th *composition symbol* of type $\langle nk_1 \cdots k_n, k \rangle$ with $k_1 = \cdots = k_n = k$. The set of all $c_{n, k}$ will be denoted by \mathbf{C} , the set of all π_i^n by Π .

$$\begin{aligned}\Sigma_{\varepsilon, 0}^L &= \Sigma'_{\varepsilon, 0} \\ \Sigma_{\varepsilon, n}^L &= \Sigma'_{\varepsilon, n} \cup \{\pi_i^n \mid 1 \leq i \leq n\} \text{ for } n \geq 1 \\ \Sigma_{nk_1 \cdots k_n, k}^L &= \{c_{n, k}\} \text{ for } n, k \geq 0 \text{ and } k_i = k \text{ for } 1 \leq i \leq n \\ \Sigma_{w, s}^L &= \emptyset \text{ otherwise}\end{aligned}$$

For $k \geq 0$, $\text{LIFT}_k^\Sigma : T(\Sigma, X_k) \rightarrow T(\Sigma^L, k)$ is defined as follows:

$$\begin{aligned}\text{LIFT}_k^\Sigma(x_i) &= \pi_i^k \\ \text{LIFT}_k^\Sigma(f) &= c_{0, k}(f') \text{ for } f \in \Sigma_0 \\ \text{LIFT}_k^\Sigma(f(t_1, \dots, t_n)) &= c_{n, k}(f', \text{LIFT}_k^\Sigma(t_1), \dots, \text{LIFT}_k^\Sigma(t_n)) \\ &\text{for } n \geq 1, f \in \Sigma_n \text{ and } t_1, \dots, t_n \in T(\Sigma, X_k)\end{aligned}$$

Note that this very general procedure allows the translation of any term over the original signature. The left hand side as well as the right hand side (RHS) of a rule of a CTFG $\Gamma = \langle \Sigma, F, X, S, P \rangle$ is just a term belonging to $T(\Sigma \cup F, X)$, but so is, e.g., any structure *generated* by Γ .

Further remarks on the observation that the result of LIFT-ing a CFTG is always a RTG can be found in Mönnich (1999).

As an example, we present the LIFTed version $\Gamma^L = \langle \Sigma^L, F^L, S', P^L \rangle$ of the CFTG Γ given in (1). The translation process for grammars has at its heart the LIFT-morphism for the translation of the alphabets of the operatives and inoperatives and the RHSs of the production rules. Since the rest of the translation follows trivially from this, we dispense with a formal definition. Note that for better readability, we omit the π_i^2 from $\Sigma_{\varepsilon, 2}^L$, all the 0- and 1-place composition symbols and the subscripts on all other composition symbols.

$$\begin{aligned}
\Sigma_{\varepsilon,0}^L &= \{\varepsilon, a', b', c', d'\} & \Sigma_{\varepsilon,2}^L &= \{\bullet'\} \\
\Sigma_{\varepsilon,4}^L &= \{\pi_1^4, \pi_2^4, \pi_3^4, \pi_4^4\} & \Sigma_{nk_1\dots k_n,k}^L &= \{c\} \text{ (for simplicity)} \\
F_{\varepsilon,1}^L &= \{S'\} & F_{\varepsilon,4}^L &= \{F'\}
\end{aligned}$$

$$\mathbf{p}^L = \left\{ \begin{array}{l}
S' \longrightarrow \varepsilon \\
S' \longrightarrow c(F', a', \varepsilon, c', \varepsilon) \\
S' \longrightarrow c(F', \varepsilon, b', \varepsilon, d') \\
F' \longrightarrow c(F', c(\bullet', a', \pi_1^4), \pi_2^4, c(\bullet', c', \pi_3^4), \pi_4^4) \\
F' \longrightarrow c(F', \pi_1^4, c(\bullet', b', \pi_2^4), \pi_3^4, c(\bullet', d', \pi_4^4)) \\
F' \longrightarrow c(\bullet', c(\bullet', c(\bullet', \pi_1^4, \pi_2^4), \pi_3^4), \pi_4^4)
\end{array} \right\} \quad (2)$$

We parallel the derivation for $aabccd$ shown in Figure 1 with this lifted grammar in Figure 2.

It has to be admitted that the use of macro-like productions is not the only device that has been employed for the purpose of providing grammar formalisms with a controlled increase of generative capacity. Alternative systems that were developed for the same purpose are e.g. tree adjoining grammars, head grammars and linear indexed grammars (cf. Vijay-Shanker and Weir, 1994). Although these systems make highly restrictive claims about natural language structure their predictive power is closely tied to the individual strategy they exploit to extend the context-free paradigm. The great advantage of the tree oriented formalism derives from its connection with *descriptive complexity theory*. Tree properties can be classified according to the complexity of logical formulas expressing them. This leads to a perspicuous and fully *grammar independent* characterization of tree families by MSO logic. Although this characterization encompasses only regular tree sets, the lifting process of the preceding section allows us to simulate the effect of macro-like productions with regular rewrite rules.

2.3 MSO Logic

MSO logic is a straightforward extension of first-order logic to include variables that range over sets (i.e., monadic predicates) and quantifiers over these variables. The particular language we will use is Rogers' variant of MSO predicate logic, $L_{K,P}^2$, with three disjoint, countable sets of *individual constants* \mathbf{K} , *monadic predicate constants* \mathbf{P} , and *individual and set valued variables* $\mathbf{X} = \mathbf{X}^0 \cup \mathbf{X}^1$; four binary predicates: *equality* \approx , plus the tree predicates

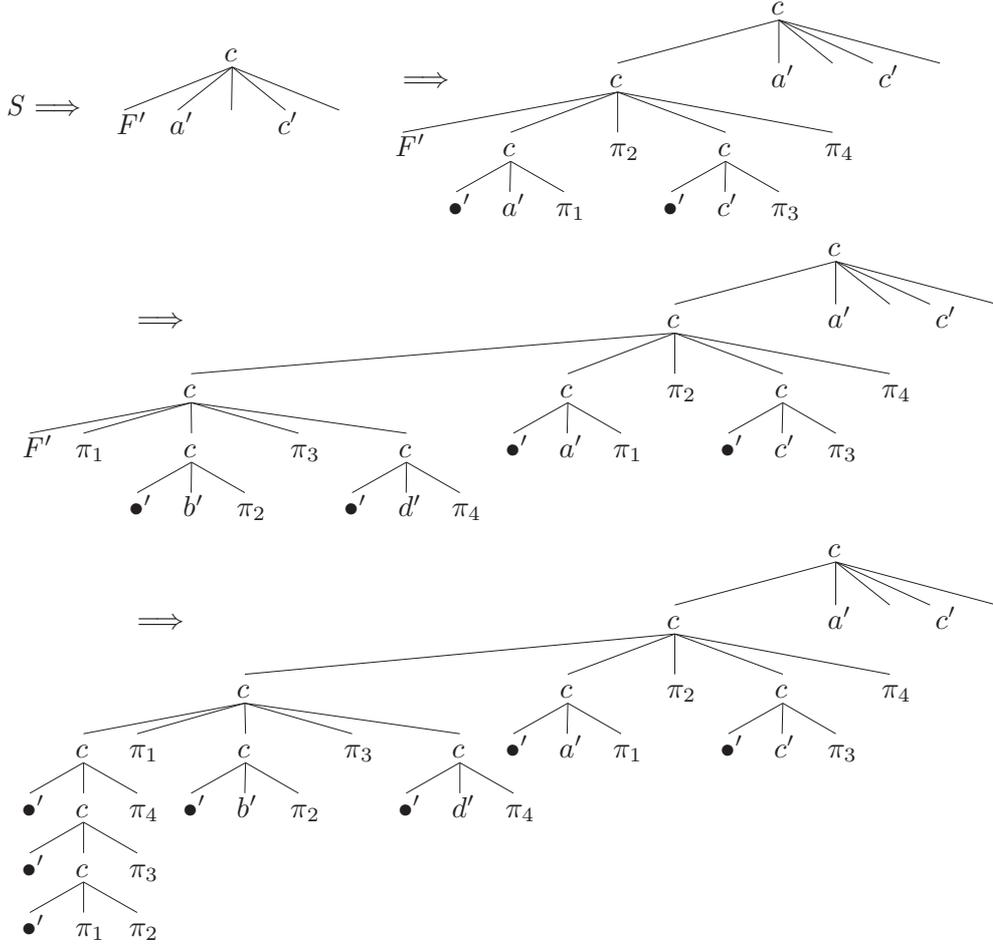


Fig. 2. A sample derivation using the LIFTed grammar

parent \triangleleft , dominance \triangleleft^* , and left-of \prec , a symbol for set membership \in and the usual connectives, quantifiers and brackets. As usual, the $k \in \mathbf{K}$ are interpreted as nodes, the $p \in \mathbf{P}$ as properties (or labels) of nodes, and the $x \in \mathbf{X}^0$ and $X \in \mathbf{X}^1$ range over nodes and sets of nodes, respectively. The syntax is the standard first order predicate logic syntax extended by quantification over monadic set variables: $\forall X \in \mathbf{X}^1$, if φ is a formula, so are $(\exists X)[\varphi]$ and $(\forall X)[\varphi]$.

No extra n -place predicates for $n > 1$ are allowed unless they are definable. We will make use of the fact that all *explicitly* definable relations and all relations which are definable by tree-walking automata (cf. Bloem and Engelfriet 1997) are definable. In contrast, addition of monadic predicates is freely allowed since they can be added to \mathbf{P} .

The intended models of $L_{K,P}^2$ are (finite) tree domains \mathbb{T} under their their natural interpretation \mathbb{T}^\natural , where \triangleleft , \triangleleft^* , \prec actually have their intuitive meaning, plus interpretations for the additional individual and predicate constants, i.e., just labeled trees (cf. Rogers 1998, for details).

The following paragraphs go directly back to Courcelle (1997). Recall that representation of objects with relational structures makes them available for the use of logical description languages. Let R be a finite set of relation symbols with the corresponding arity for each $r \in R$ given by $\rho(r)$. A relational structure $\mathcal{R} = \langle D_{\mathcal{R}}, (r_{\mathcal{R}})_{r \in R} \rangle$ consists of the domain $D_{\mathcal{R}}$ and the $\rho(r)$ -ary relations $r_{\mathcal{R}} \subseteq D_{\mathcal{R}}^{\rho(r)}$.

The classical technique of interpreting a relational structure within another one forms the basis for MSO transductions. Intuitively, the output tree is interpreted on the input tree. E.g., suppose that we want to transduce the input tree t_1 into the output tree t_2 . The nodes of the output tree t_2 will be a subset of the nodes from t_1 specified with a unary MSO relation ranging over the nodes of t_1 . The daughter relation will be specified with a binary MSO relation with free variables x and y ranging over the nodes from t_1 . We will use this concept to transform the lifted trees into the intended ones.

A (non-copying) MSO transduction of a relational structure \mathcal{R} (with set of relation symbols R) into another one \mathcal{Q} (with set of relation symbols Q) is defined to be a tuple $(\varphi, \psi, (\theta_q)_{q \in Q})$ consisting of an MSO formula φ defining the domain of the transduction in \mathcal{R} , an MSO formula ψ defining the resulting domain of \mathcal{Q} , and a family of MSO formulas θ_q defining the new relations Q using only definable formulas from the “old” structure \mathcal{R} .

In this sense, our logical description of non-context-free phenomena with two devices with only regular power is an instance of the theorem that the image of an MSO-definable class of structures under a definable transduction is not MSO definable in general (Courcelle, 1997).

2.4 Automata and Transducers

Tree automata are the result of generalizing the transition function of standard finite-state automata from (state-alphabet) symbol pairs to tuples of states. Intuitively, a bottom-up tree automaton creeps up a tree from the leaves to the root by simultaneously taking the states of the daughters and the alphabet symbol of the mother to make a transition to a new state.

Definition 7 (Tree Automaton) A (deterministic) bottom-up tree automaton \mathfrak{A} is a 5-tuple $\langle Q, \Sigma, \delta, a_0, Q_f \rangle$ with Q the (finite) set of states, Σ a ranked alphabet, $a_0 \in Q$ the initial state, $Q_f \subseteq Q$ the final states and $\delta : \bigcup_n (Q^n \times \Sigma_n) \rightarrow Q$ the transition function.

We can extend the transition function inductively to trees by defining $h_\delta(\varepsilon) = a_0$ and $h_\delta(\sigma(t_1, \dots, t_n)) = \delta(h_\delta(t_1), \dots, h_\delta(t_n), \sigma)$, $t_i \in T(\Sigma)$, $1 \leq i \leq n$, $\sigma \in \Sigma$.

Σ_n . An automaton \mathfrak{A} accepts a tree $t \in T(\Sigma)$ iff $h_\delta(t) \in Q_f$. The language recognized by \mathfrak{A} is denoted by $T(\mathfrak{A}) = \{t \mid h_\delta(t) \in Q_f\}$.

The sets of trees recognized by bottom-up tree automata are called recognizable, i.e., regular sets of trees, and, as mentioned previously, yield context-free string languages (Gécseg and Steinby, 1984). The recognizable sets are closed under the boolean operations of conjunction, disjunction and negation. The automata constructions which underlie these closure results are generalizations of the corresponding better-known constructions for finite state automata (FSA). The recognizable sets are also closed under (inverse) projections, and again the construction is essentially that for finite state automata. The projection construction yields a nondeterministic automaton, but, again as for FSA's, bottom-up tree automata can be made deterministic by a straightforward generalization of the subset construction.² Finally, tree automata can be minimized by a construction which is, yet again, a straightforward generalization of well known FSA techniques.

We need another type of finite-state machine later in the paper: Macro Tree Transducer (MTTs). Since those are not so well known, we will introduce them via the more accessible standard top-down tree transducers. These are not so different from the bottom-up tree automata introduced above. Instead of working from the leaves towards the root, the top-down tree transducer start from the root and work their way downwards to the leaves. And, of course, they produce an output tree along the way. In the following paragraphs we will use the notation as introduced in Engelfriet and Vogler (1985). Our presentation is also inspired by Engelfriet and Maneth (2000). A full introduction to tree transductions can be found in Gécseg and Steinby (1997).

Intuitively, top-down tree transducers transform trees over a ranked alphabet Σ into ones over a ranked alphabet Ω . They traverse a tree from the root to the leaves (the input tree) and output on each transition step a new tree whose nodes can contain labels from both alphabets, states and variables. More formally, the right hand sides of such a production are trees from $T(\Omega \cup \Sigma(X) \cup Q)$. For this definition we assume that Q is a ranked alphabet containing only unary symbols.³

Definition 8 (Top-Down Tree Transducer) A top-down tree transducer (TDTT) is a tuple $T = \langle Q, \Sigma, \Omega, q_0, P \rangle$ with states Q , ranked alphabets Σ and Ω (input and output), initial state q_0 and a finite set of productions P of

² Note that *top-down* tree automata do not have this property: deterministic top-down tree automata recognize a strictly narrower family of tree sets.

³ As we will indicate in Section 5.2, sort distinctions can be disregarded for our purposes.

the form

$$q(\sigma(x_1, \dots, x_n)) \longrightarrow t$$

where $n \geq 0$, $\sigma \in \Sigma_n$ and $t \in T(\Omega \cup \Sigma(X) \cup Q)$.

The transition relation (\xRightarrow{T}) is defined as usual. The transduction realized by a top-down tree transducer T is then defined to be $\{(t_1, t_2) \in T(\Sigma) \times T(\Omega) \mid q_0(t_1) \xRightarrow{T}^* t_2\}$.

Consider as a very simple example the transducer T which maps binary trees whose interior nodes are labeled with a 's into ternary trees whose interior nodes are labeled with b 's. The leaves are labeled with p and are transduced into q 's. Furthermore, new leaves labeled c are introduced at every branching point. Σ consists of one binary symbol a and one constant p , Ω of one ternary symbol b and two constants q and c . The transducer has only one state q_0 and the two productions below:

$$\begin{aligned} q_0(a(x_1, x_2)) &\longrightarrow b(q_0(x_1), c, q_0(x_2)) \\ q_0(p) &\longrightarrow q \end{aligned}$$

Figure 3 shows one application of the nontrivial rule. The left hand side displays the rule in tree notation whereas the right hand side displays an actual transition.

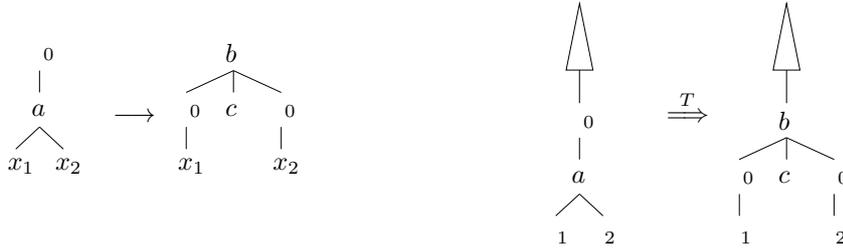


Fig. 3. One step of an TDTT derivation

If we have already transduced a subtree β of the input and are in state q_0 and currently working on a node labeled with a with immediate subtrees t_1 and t_2 , then we can rewrite it into a tree labeled with b whose leftmost and rightmost daughter are in state q_0 applied to t_1 and t_2 respectively and the middle daughter is labeled with the terminal symbol c .

By generalizing the set of states to a ranked alphabet, we can extend the notion of a top-down tree transducer to a macro tree transducer. This allows to pass parameters—which contain a limited amount of context from the part of the input tree we have already seen—into the right hand sides. We formalize these new right hand sides as follows:

Definition 9 Let Σ and Ω be ranked alphabets and $n, m \geq 0$. The set of right hand sides $RHS(\Sigma, \Omega, n, m)$ over Σ and Ω with n variables and m parameters

is the smallest set $rhs \subseteq T(\Sigma \cup \Omega, X_n \cup Y_m)$ such that

- (i) $Y_m \subseteq rhs$
- (ii) For $\omega \in \Omega_k$ with $k \geq 0$ and $\varphi_1, \dots, \varphi_k \in rhs$, $\omega(\varphi_1, \dots, \varphi_k) \in rhs$
- (iii) For $q \in Q_{k+1}$ with $k \geq 0$, $x_i \in X_n$ and $\varphi_1, \dots, \varphi_k \in rhs$,
 $q(x_i, \varphi_1, \dots, \varphi_k) \in rhs$

The productions of macro tree transducers contain one “old” parameter (an alphabet symbol with the appropriate number of variables) and additionally a number of context parameters.

Definition 10 (Macro Tree Transducer) A macro tree transducer (MTT) is a five-tuple $M = \langle Q, \Sigma, \Omega, q_0, P \rangle$ with Q a ranked alphabet of states, ranked alphabets Σ and Ω (input and output), initial state q_0 of rank 1, and a finite set of productions P of the form

$$q(\sigma(x_1, \dots, x_n), y_1, \dots, y_m) \longrightarrow t$$

where $n, m \geq 0$, $q \in Q_{m+1}$, $\sigma \in \Sigma_n$ and $t \in RHS(\Sigma, \Omega, n, m)$.

The productions $p \in P$ of M are used as term rewriting rules in the usual way. The transition relation of M is denoted by \xrightarrow{M} . The transduction realized by M is the function $\{(t_1, t_2) \in T(\Sigma) \times T(\Omega) \mid (q_0, t_1) \xrightarrow{M}^* t_2\}$.

Generally, just as for CFTGs, a little care has to be taken in the definition of the transition relation with respect to the occurring parameters y_i . Derivations are dependent on the order of tree substitutions. Inside-out means that trees from $T(\Omega)$ have to be substituted for the parameters whereas in outside-in derivations any subtree must not be rewritten if it is in some context parameter. Neither of these classes contains the other. Since we are only dealing with *simple* MTTs in our approach, all modes are equivalent and can safely be ignored.

An MTT is *deterministic* if for each pair $q \in Q_{m+1}$ and $\sigma \in \Sigma_n$ there is at most one rule in P with $q(\sigma(x_1, \dots, x_n), y_1, \dots, y_m)$ on the left hand side.

An MTT is called *simple* if it is simple in the input (i.e., for every $q \in Q_{m+1}$ and $\sigma \in \Sigma_n$, each $x \in X_k$ occurs exactly once in $RHS(\Sigma, \Omega, n, m)$) and simple in the parameters (i.e., for every $q \in Q_{m+1}$ and $\sigma \in \Sigma_k$, each $y \in Y_m$ occurs exactly once in $RHS(\Sigma, \Omega, n, m)$). The MTT discussed in the remainder of the paper will be simple. Note that if we disregard the input, MTTs turn into CFTGs.

Consider for example the following rule of an MTT M .

$$q_0(a(x_1, x_2), y_1, y_2, y_3) \longrightarrow b(x_1, b(q_0(y_1)), q_0(y_2), y_3, q_0(x_2))$$

Analogous to the presentation in Figure 3, we illustrate the the rule above in Figure 4 without being too concerned about the formal details of specifying a full transducer.

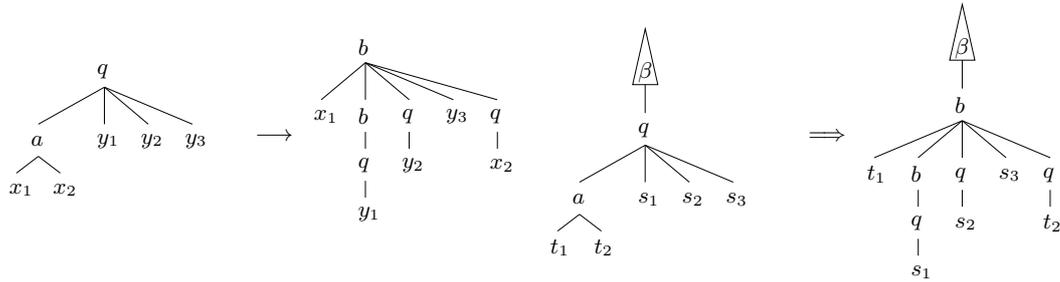


Fig. 4. One step of an MTT derivation

The only difference (apart from a totally different transduction) is that we now have parameters which appear as trees s_1 through s_3 . Those trees can also be freely used on the right hand sides of the MTT productions.

3 Linguistic Motivation: Cross-Serial Dependencies

As mentioned in the introduction, the exercise in formal coding is made necessary by the fact that natural language sports some constructions which lead (i) to non-context-free string languages, or (ii) to at least non-recognizable tree languages (i.e., tree sets which cannot be generated by any context-free string grammar or regular tree grammar), even though the resulting string languages may formally be context-free.⁴ Both phenomena show up in the West-Germanic languages: the verbal complex of Züritüütsch, a variant of Swiss German spoken around Zürich, is an example of (i), while (ii) is exhibited—for different reasons—by the corresponding constructions of Dutch and Standard German (Huybregts, 1976; 1984):

(3) a. weil der Karl die Maria dem Peter den Hans schwimmen

because Charles Mary₁ Peter₂ John₃ swim₃-inf

lehren helfen läßt

teach₂-inf help₁-inf lets

(*German fragment as string language: Palindrome language—CF*)

⁴ Let us note here that it is not the goal of this section to attempt a linguistically relevant discussion of cross-serial dependencies. All we want to show is that a formalism for natural languages has to handle non-context-free structures and how our proposal could do it. For a serious introduction of approaches to cross-serial dependencies see Pullum and Gazdar (1982).

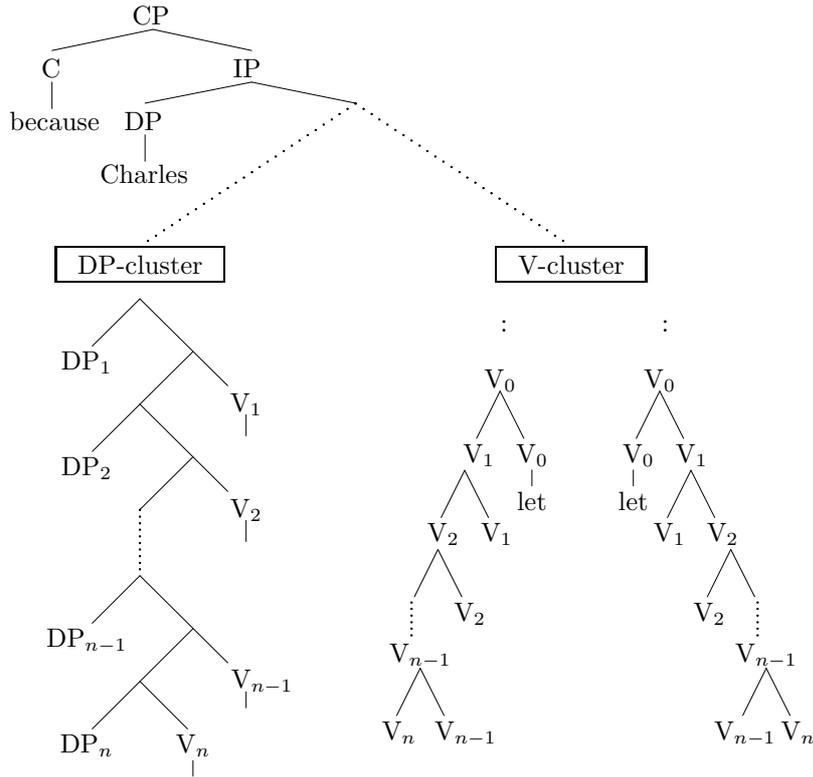
- b. omdat Karel Marie Piet Jan laat helpen leren zwemmen
 because Charles Mary₁ Peter₂ John₃ lets help₁-inf teach₂-inf swim₃-inf
(Dutch fragment as string language: $a^n b^n$ —CF)
- c. wil de Karl d’Maria em Peter de Hans laat hälffe lärne
 because Charles Mary₁ Peter₂ John₃ lets help₁-inf teach₂-inf
 schwüme
 swim₃-inf
(Züritüütsch fragment as string language: $a^n b^m c^n d^m$ —Non-CF)
 ‘because Charles lets Mary help Peter to teach John to swim’

The structure of the preceding example illustrates what we encountered in the artificial example in (1). On a close look at, e.g., the Swiss German example, we note that the DP’s and the V’s of which the DP’s are objects occur in cross-serial order. This is manifested by the case marking of the respective objects. Empirical analysis shows that there are no limits on the length of such constructions in grammatical sentences of Swiss German. This fact alone would not suffice to prove that Swiss German is not a context-free string language. It could still be the case that Swiss German *in toto* is context-free even though it subsumes an isolable context-sensitive fragment. Relying on the closure of context-free languages under intersection with regular languages, Shieber (1985) was able to show that not only the fragment exhibiting the cross-serial dependencies but the whole of the language has to be assumed as non context-free.⁵

Abstracting from the details of the particular languages, the standard analyses of these constructions involve the following property which is problematic from the point of view of context-freeness: In all cases they posit roughly a bipartite structure like the one in Figure 5 with basically all DP’s on one branch and all the verbs on the other—but with fixed syntactic and semantic relations between the branches, whether visibly marked (as in Züritüütsch, Standard German) or not (Dutch).

As is easily seen, there is no context-free device which could directly handle the unbounded number of non-local dependencies the structural separation of the two “clusters” enforces. Therefore MSO logic alone cannot be sufficient for linguistic reasons. But in order to concentrate on the relevant details, we

⁵ Huybregts (1984) provides a similar argument for Dutch taking into account a particular fragment: in contrast to Swiss German, Dutch does not show overt case-marking of objects. Huybregts argument crucially relies on a given morphologized—and thus syntactical—difference between animate and inanimate pronominals.



	overt case	V-cluster
German	+	α
Dutch	-	β
Züritüütsch	+	β

Fig. 5. The structure of Germanic VR

will use the artificial example from (1) in the following sections to illustrate our proposal.

There is an ongoing discussion on how much power “beyond context-free string grammars” a formal device must provide in order to handle all linguistic phenomena adequately. The formalism of, e.g., minimalist grammars (MGs) in the sense of Stabler (1997) is certainly able to cope with cross-serial dependencies.⁶ In Michaelis (1999) it has been shown that MGs can be translated into the—compared to CFTGs—weaker formalism of multiple context-free grammars (Seki et al., 1991). In Michaelis et al. (2000c) we have shown how MGs can be treated within an approach similar to the one we present here by using this translation and by applying a lifting process to MCFGs afterwards.

⁶ MGs provide an attempt of a rigorous algebraic formalization of the new linguistic perspective which reflects the change within the linguistic framework of transformational grammar from GB-theory to minimalism.

Therefore, context-free tree grammars may be too strong for an adequate characterization of the complexity of natural languages. On the other hand, certain phenomena like the widely discussed cases of *Suffixaufnahme* (multiple case-stacking) seem to indicate that natural languages are not semilinear (cf. Michaelis and Kracht (1997)), and it is well known that the Parikh images of string languages generated by multiple context-free grammars are semilinear. Inside-out context-free tree languages in their turn are sufficiently powerful to handle the known cases of *Suffixaufnahme* as has been shown in Mönnich (1997).

4 A Tree Automaton and an MSO formula for Regular Tree Sets

Since Γ^L in (2) generates a regular set of trees, we can construct a tree automaton $\mathfrak{A}_{\Gamma^L} = \langle Q, \Sigma, \delta, q_0, Q_f \rangle$ to recognize this set.

Construction of a tree automaton from a given lifted context-free tree grammar $\Gamma^L = \langle \Sigma^L, F^L, S', P^L \rangle$, i.e., an RTG, is straightforward. Intuitively, since tree automata recognize only local trees in each transition, we have to use auxiliary transitions for RHSs of LIFTed macro productions with trees of depth greater than one in order to recognize the right trees incrementally. So, what we are doing is to decompose the RHSs into trees of depth one which then can be recognized by a transition, i.e., in a preliminary step we have to transform Γ^L into a normal form $\Gamma^{NF} = \langle \Sigma^L, F^{NF}, S', P^{NF} \rangle$ via the introduction of auxiliary rules and new nonterminals. In our example, the lifted tree grammar is not in the desired normal form, but it is easy to see how to change this.⁷ The resulting rules and nonterminals are reflected both in the new transitions and in the states we need. In the following, we assume without loss of generality, that the trees on the RHSs of the LIFTed macro productions are of depth one.

Recall that, according to the definition above, a tree automaton operates on a ranked alphabet $\Sigma = \langle \Sigma_n \mid n \in \mathbb{N} \rangle$. Therefore, in our case, we use the inoperative symbols of the lifted grammar to construct Σ , but we reduce the explicit many-sorted type information by defining Σ_n as $\{\sigma \in \Sigma^L \mid \text{rank}(\sigma) = n\}$. For the set of states Q , we need distinguishable states for each of the terminals, nonterminals and projection symbols appearing in RHSs of the rules, i.e., $Q = \{q_\sigma \mid \sigma \in \Sigma_{\varepsilon,s}^L \cup F^{NF}\} \cup \{q_0\}$.⁸ Furthermore, we need a new initial state

⁷ For example, the production for $F' \longrightarrow c(F', c(\bullet', a', \pi_1^4), \pi_2^4, c(\bullet', c', \pi_3^4), \pi_4^4)$ is transformed into the following two new productions: $F' \longrightarrow c(F', C_a, \pi_2^4, C_c, \pi_4^4)$, $C_a \longrightarrow c(\bullet', a', \pi_1^4)$ and $C_c \longrightarrow c(\bullet', c', \pi_3^4)$. The full translation of the other productions into the corresponding normal form is left to the reader.

⁸ We do not need states for the composition symbols since each composition corresponds to a nonterminal due to the normal form.

$$\mathfrak{A}_{\Gamma^L} = \langle Q, \Sigma, \delta, q_0, \{q_{S'}\} \rangle$$

$$\delta : \bigcup_{1 \leq n \leq 5} Q^n \times \Sigma \rightarrow Q$$

$$\begin{array}{ll} (q_0, \epsilon) \rightarrow q_\epsilon & (q_{\bullet'}, q_{a'}, q_{\pi_1}, c) \rightarrow q_{C_a} \\ (q_0, a') \rightarrow q_{a'} & (q_{\bullet'}, q_{c'}, q_{\pi_3}, c) \rightarrow q_{C_c} \\ (q_0, b') \rightarrow q_{b'} & (q_{\bullet'}, q_{b'}, q_{\pi_2}, c) \rightarrow q_{C_b} \\ (q_0, c') \rightarrow q_{c'} & (q_{\bullet'}, q_{d'}, q_{\pi_4}, c) \rightarrow q_{C_d} \\ (q_0, d') \rightarrow q_{d'} & (q_{\bullet'}, q_{\pi_1}, q_{\pi_2}, c) \rightarrow q_{C_2} \\ (q_0, \pi_1) \rightarrow q_{\pi_1} & (q_{\bullet'}, q_{C_2}, q_{\pi_3}, c) \rightarrow q_{C_3} \\ (q_0, \pi_2) \rightarrow q_{\pi_2} & (q_{\bullet'}, q_{C_3}, q_{\pi_4}, c) \rightarrow q_{F'} \\ (q_0, \pi_3) \rightarrow q_{\pi_3} & (q_{F'}, q_{\pi_1}, q_{C_b}, q_{\pi_3}, q_{C_d}, c) \rightarrow q_{F'} \\ (q_0, \pi_4) \rightarrow q_{\pi_4} & (q_{F'}, q_{C_a}, q_{\pi_2}, q_{C_c}, q_{\pi_4}, c) \rightarrow q_{F'} \\ (q_0, \bullet') \rightarrow q_{\bullet'} & (q_{F'}, q_\epsilon, q_b, q_c, q_d, c) \rightarrow q_{S'} \\ (q_0, \epsilon) \rightarrow q_{S'} & (q_{F'}, q_a, q_\epsilon, q_c, q_\epsilon, c) \rightarrow q_{S'} \end{array}$$

Fig. 6. The tree automaton for Γ^L

q_0 . In the automaton, the state which corresponds to the start symbol S' of the grammar becomes the single final state, i.e., $Q_f = \{q_{S'}\}$.

Since our tree automata work bottom up, we have to start the processing at the bottom by having transitions from the new initial state to a new state encoding that we read a particular symbol on the frontier of the tree. So, together with the transitions encoding the productions, we have to construct two kinds of transitions in δ :

- transitions from the initial state on all subtrees reading a terminal symbol σ , i.e., elements of all the Σ_i from Γ , to the corresponding state; i.e., $q_0 \times \sigma \rightarrow q_\sigma$;
- transitions recognizing the internal structure of the local trees appearing in RHSs, i.e., from the states corresponding to the leaves of a tree on a RHS to the nonterminal D of the left hand side, i.e., for each lifted tree grammar production of depth one $D \rightarrow c(d_1, \dots, d_n)$ we have to construct a transition in the automaton which looks as follows: $q_{d_1} \times \dots \times q_{d_n} \times c \rightarrow q_D$.

Accordingly, the tree automaton corresponding to the RTG Γ^L given in (2) looks as given in Figure 6. Obviously the automaton recognizes the same set of trees.

In Thomas (1990) tree automata are converted to formulas in MSO logic by basically encoding their behaviour. Under the assumption that $Q = \{0, \dots, m\}$ with $q_0 = 0$, the (closed) Σ_1^1 -formula $\varphi_{\mathfrak{A}_{\Gamma^L}}$ given there adapted to our signature and for maximally 5-ary tree automata looks as given in (4).⁹

⁹ P_a stands for the predicate labeling a node with the symbol a and $\text{leaf}(x) \stackrel{\text{def}}{\iff} (\neg \exists y)[x \triangleleft y]$.

Intuitively, the sets X_i label the tree where the automaton assumes state i . The first two lines of the formula says that we cannot have a node which is in two states and that X_0 is our “initial” set; the second one licenses the distribution of the sets according to the transitions and the last one says that we need a root node which is in a “final” set.

$$\begin{aligned}
\varphi_{\mathfrak{A}_{T^L}} \stackrel{def}{\iff} & (\exists X_0, \dots, X_m) [\bigwedge_{i \neq j} (\neg \exists y) [y \in X_i \wedge y \in X_j] \wedge \\
& (\forall x) [\text{leaf}(x) \rightarrow x \in X_0] \\
& \bigwedge_{1 \leq l \leq 5} (\forall x_1, \dots, x_l, y) [\bigvee_{\substack{(i_1, \dots, i_l, \sigma, j) \in \delta \\ 1 \leq k \leq l}} x_k \in X_{i_k} \wedge y \triangleleft x_k \wedge y \in X_j \wedge y \in P_\sigma] \\
& \bigvee_{i \in Q_f} (\exists x \forall y) [x \triangleleft^* y \wedge x \in X_i]
\end{aligned} \tag{4}$$

5 Reconstructing the Intended Trees

Unfortunately, the terminal trees in Figure 2, generated/recognized by (2) or the tree automaton in Figure 6, don’t seem to have much in common with the structures linguists want to talk about, i.e., the ones in Figure 1.

However, in some sense to be made operational, the Γ^L structures contain the intended structures. As mentioned before, there is a mapping h from these explicit structures onto structures interpreting the $c \in \mathbb{C}$ and the $\pi \in \Pi$ the way the names we have given them suggest, *viz.* as compositions and projections, respectively, which are, in fact, exactly the intended structures.

On the denotational side, we will use an MSO definable tree transduction (as defined in Section 2.3) and operationally we will use a Macro Tree Transducer (see Section 2.4) to transform the LIFTed structures into the intended ones.

5.1 The MSO Transduction

As mentioned in the preliminaries, Rogers (1998) has shown the suitability of an MSO description language $L_{K,P}^2$ for linguistics which is based upon the primitive relations of immediate (\triangleleft), proper (\triangleleft^+) and reflexive (\triangleleft^*) dominance and proper precedence (\prec). We will show how to define these relations with an MSO transduction thereby implementing the unique homomorphism mapping the terms into elements of the corresponding context-free tree language, i.e., the trees linguists want to talk about.

Put differently, it should be possible to define a set of relations $R^I = \{\triangleleft, \triangleleft^+, \triangleleft^*\}$

(*dominance*), *c-command*, \triangleleft (*precedence*), ...} holding between the nodes $n \in N^L$ of the explicit or LIFTed tree T^L which carry a “*linguistic*” label L in such a way, that when interpreting $\triangleleft^* \in R^I$ as a tree order on the set of “*linguistic*” nodes and $\triangleleft \in R^I$ as the precedence relation on the resulting structure, we have a “new” description language on the intended structures.

We have shown in Kolb et al. (2000) how to give an operational account of an MSO transduction to recover the intended relations via so called tree-walking automata with MSO tests.¹⁰ In this paper, we will present the logical aspect of this transduction without going into the details of how to generate the relevant formulas. The interested reader is referred to the reference given above.

We will use $\text{trans}_{W_{\triangleleft}}(x, y)$ as the formula denoting immediate dominance ($x \triangleleft y$) on the intended structures. This formula was constructed recursively from the walking language of a tree-walking automaton linking the appropriate nodes in the lifted tree. An example of these relations is displayed graphically in Figure 7 which contains another rendering of the last tree of the derivation given in Figure 2. The intended dominance relation marks the endpoints of these tree walks.

Suppose we want to find the two daughters of the “second” concatenation symbol (\bullet). What we have to do is find its sisters and use them as the immediate daughters of the concatenation. If these nodes are labeled with a “*linguistic*” label, we are done, if not we have to find the appropriate nodes recursively.¹¹ The easy case of a composition symbol entails simply taking its leftmost daughter. The more problematic case of finding the appropriate filler for a node labeled with a projection symbol is illustrated with the π_3 - and π_1 -links where we have to recursively traverse the tree (more on the details of how to find these can be found in Kolb et al. (2000); Michaelis et al. (2000a,b)). The resulting immediate dominance links are indicated by the grey lines. While we have been sloppy with regard to the subscripts of the compositions so far, we are more precise in this figure and give the exact labeling for reasons which will become clear when we define the macro tree transducer.

Presupposing this definition of immediate dominance, we can define the other relations we need for the MSO transduction as follows.

For the case of the recursion inherent in reflexive dominance a standard solution exists in MSO logic on finite trees. It is a well-known fact (e.g., Courcelle

¹⁰ A tree-walking automaton with MSO tests is a finite state automaton which can navigate through a tree by following simple directives or by testing properties of nodes via MSO formulas. Bloem and Engelfriet (1997) show that the relations between two nodes recognized by their walks is constructively MSO definable.

¹¹ This recursion makes the use of the tree-walking automata imperative since in general MSO relations cannot be defined recursively.

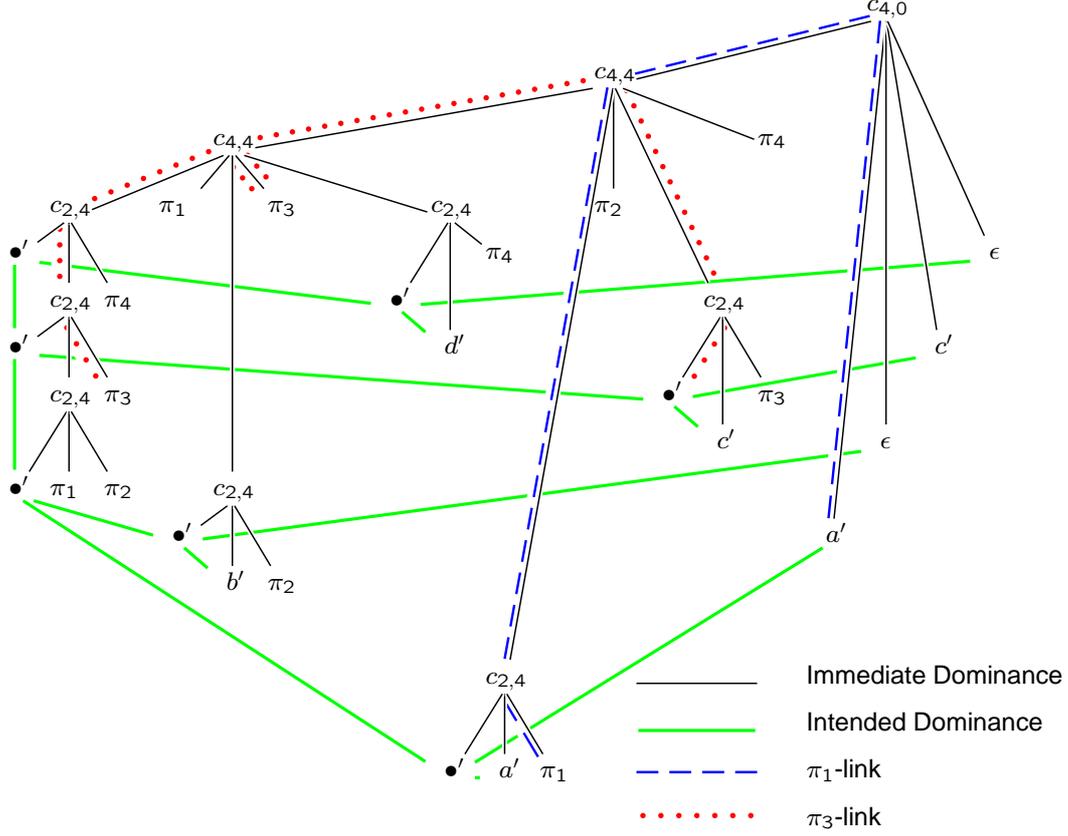


Fig. 7. Intended relations on a LIFTed structure

1990) that the reflexive transitive closure R^* of a binary relation R on nodes is (weakly) MSO-definable, if R itself is. This is done via a second-order property which holds of the sets of nodes which are closed under R :

$$R\text{-closed}(X) \stackrel{def}{\iff} (\forall x, y)[x \in X \wedge R(x, y) \rightarrow y \in X] \quad (5)$$

Now, for any node n , the intersection of all such sets which contain n is exactly the set of m , such that $R^*(n, m)$. Since we are dealing with the (necessarily finite) trees generated by a context-free tree grammar, this construction can be safely exploited for our purposes; \blacktriangleleft^* and \blacktriangleleft^+ can be defined as follows:

Reflexive Dominance:

$$x \blacktriangleleft^* y \stackrel{def}{\iff} (\forall X)[\blacktriangleleft\text{-closed}(X) \wedge x \in X \rightarrow y \in X] \quad (6)$$

Proper dominance:

$$x \blacktriangleleft^+ y \stackrel{def}{\iff} x \blacktriangleleft^* y \wedge x \not\approx y$$

Using the defined formula $\text{trans}_{W_{\blacktriangleleft}}(x, y)$ for \blacktriangleleft , the specific MSO transduction we need to transform the LIFTed structures into the intended ones looks as follows:

$$(\varphi, \psi, (\theta_q)_{q \in Q})$$

$$Q = \{\triangleleft, \triangleleft^*, \triangleleft^+, \triangleleft, \dots\}$$

$$\begin{aligned} \varphi &\equiv \varphi_{\mathfrak{A}_{\Gamma L}} \\ \psi(x) &\equiv (\exists y)[x \triangleleft y \vee y \triangleleft x] \\ \theta_{\triangleleft}(x, y) &\equiv \text{trans}_{W_{\triangleleft}}(x, y) \\ \theta_{\triangleleft^*}(x, y) &\equiv (\forall X)[\triangleleft\text{-closed}(X) \wedge x \in X \rightarrow y \in X] \\ \theta_{\triangleleft^+}(x, y) &\equiv x \triangleleft^* y \vee x \not\sim y \\ \theta_{\triangleleft}(x, y) &\equiv \text{trans}_{W_{\triangleleft}}(x, y) \\ \theta_{L \in \text{Labels}}(x) &\equiv L(x) \end{aligned} \tag{7}$$

As desired, the domain of the transduction is characterized by the MSO formula for the LIFTed trees (see Section 4). The domain, i.e., the set of nodes, of the intended tree is characterized by the formula ψ which identifies the nodes with a “linguistic” label which stand indeed in the new dominance relation. Building on it, we define the other primitives of our description language analogous to the MSO language $L_{K,P}^2$ used to analyze large parts of GB theory in Rogers (1998). For reasons of space, we have to leave the specification of the precedence relation $\text{trans}_{W_{\triangleleft}}(x, y)$ open. It is more complicated than dominance, but can be achieved with another tree-walking automaton.¹² Finally, the labeling information for the nodes is taken over from R .

Note also that while standardly “linguistic” relations like *c-command* or *government* would be defined in terms of *dominance*, our approach allows the alternative route of taking, in the spirit of Frank and Vijay-Shanker (1998), *c-command* as the primitive relation of linguistic structure by defining, in a similar, though—since Chomsky’s (1985) distinction between *segments* and *categories* has to be accommodated—somewhat more complicated fashion, an automaton $\mathfrak{A}_{c\text{-command}}$, which computes the intended *c-command* relation directly, without recourse to dominance.

5.2 The Macro Tree Transducer

As stated previously, there is a *unique* morphism h from the “lifted” terms over the derived alphabet Σ^L into the terms over the tree substitution algebra,

¹² This is certainly true for LIFTed structures resulting from *linear* context-free tree grammars. For non-linear ones, we have to take each individual run of the automaton into consideration which complicates matters considerably.

where $c(t, t_1, \dots, t_k)$ for $t \in T(\Sigma, X_k)$, $t_1, \dots, t_k \in T(\Sigma, X_m)$ denotes the result of *substituting* t_i for x_i in t .

The morphism h is defined inductively as follows:

$$\begin{aligned} h(f') &= f(x_1, \dots, x_n) \text{ for } f \in \Sigma_n \\ h(\pi_i^n) &= x_i \\ h(c(t, t_1, \dots, t_n)) &= h(t)[h(t_1), \dots, h(t_n)] \end{aligned} \tag{8}$$

where $t[t_1, \dots, t_n]$ denotes the result of substituting t_i for x_i in t for $t \in T(\Sigma, X_k)$, $t_i \in T(\Sigma, X_m)$.¹³

Let $\tilde{\Sigma}^L = \langle \tilde{\Sigma}_n^L \mid n \in \mathbb{N} \rangle$ be the ranked alphabet with $\tilde{\Sigma}_n^L = \{\sigma \in \Sigma^L \mid \text{rank}(\sigma) = n\}$. The unique morphism h can be performed by a simple macro tree transducer $M = \langle Q, \tilde{\Sigma}^L, \Sigma, q_0, P \rangle$, where $Q = \{q_n \mid n \text{ the rank of some element in } \tilde{\Sigma}^L\}$, q_0 is the initial state and P is a finite family of rules.

The MTT which we construct to carry out the transformation effected by the unique homomorphism h combines in a particularly perspicuous way the actions of a top-down finite tree transducer—based upon the syntactic structure of the lifted alphabet Σ^L —and the production aspect of the underlying CFTG via its (i.e., the MTT's) dependence on the local context (parameters): retrieving the “old” arity out of the new sorted constants of the signature Σ^L .

How can we construct the necessary productions to recover the intended trees? We take an intuitive approach to explaining the construction of the needed MTT which is strongly dependent on inspection of the tree in Figure 7.

In general, in the first argument we will have a tree during a transduction. So in the rules, we have to take care of all symbols which can appear as mothers of (possibly trivial) trees with the number of variables corresponding to their arities in the first argument of any left hand side.

After careful inspection of the tree language generated by the lifted RTG Γ^L , the simplest case is certainly when we are faced with a constant from $\tilde{\Sigma}_0^L$. In this case all we have to do is to map it back to the corresponding element from Σ , regardless of the parameters, if there are any. In case we encounter a projection symbol we simply have to return the corresponding parameter. Obviously, this presupposes that we stored the “right” information there.

Furthermore, all rules with a symbol whose “unlifted” version was not a constant will have as many parameters as are needed to compute the correspond-

¹³ It is immediately obvious how one can translate this recursive definition into a simple Prolog program. But since we can simulate a Turing machine with Prolog, nothing much is gained on the formal side. In case one considers implementing the approach, it makes sense to use this simple homomorphism directly.

ing function, e.g., \bullet obviously is binary and therefore needs two parameters (see the last rule in (9)). The resulting rule has, on the right hand side, simply the “executed” function.

For the rules headed by a composition symbol $c_{n,k}$ we need as many parameters as are prescribed by k . This is due to the fact that while generally the relevant information in the lifted trees is on the leftmost branch, we nevertheless need the other daughters to be able to unravel the projections. Basically, we follow a depth-first strategy on the leftmost component of the lifted trees while still passing the necessary context (i.e., the evaluation of the computation of the other daughters) down into that computation.

Similarly, we also get the necessary states from the arities of the composition symbols. The rules then simply pass the state and the parameters of the left hand side of the rule to the arguments of the alphabet symbol while continuing to work on the first argument. As an example consider an $n + 1$ branching fork whose mother is labeled with $c_{n,k}$. Then we have to construct a rule which has on the left hand side state q_k with arity $k + 1$. It has as its first argument a term with functor $c_{n,k}$ and arguments x_1, \dots, x_{n+1} . The other arguments are the parameters y_1 to y_k . The right hand side has state q_n of arity $n + 1$ with the first argument simply being x_1 and the other arguments being $q_k(x_i, y_1, \dots, y_k)$, $1 < i \leq n + 1$.

For our concrete example, the set of rules P of the MTT M look as given below:

$$\begin{aligned}
& q_0(c_{4,0}(x_1, x_2, x_3, x_4, x_5)) \longrightarrow \\
& \quad q_4(x_1, q_0(x_2), q_0(x_3), q_0(x_4), q_0(x_5)) \\
& \quad \quad q_0(\sigma') \longrightarrow \sigma \quad \text{for } \sigma \in \{a, b, c, d, \varepsilon\} \\
& q_4(c_{4,4}(x_1, x_2, x_3, x_4, x_5), y_1, y_2, y_3, y_4) \longrightarrow \\
& \quad q_4(x_1, q_4(x_2, y_1, y_2, y_3, y_4), q_4(x_3, y_1, y_2, y_3, y_4), \\
& \quad \quad q_4(x_4, y_1, y_2, y_3, y_4), q_4(x_5, y_1, y_2, y_3, y_4)) \quad (9) \\
& \quad q_4(P_i, y_1, y_2, y_3, y_4) \longrightarrow y_i \quad \text{for } P_i = \pi_i \\
& \quad q_4(\sigma', y_1, y_2, y_3, y_4) \longrightarrow \sigma \quad \text{for } \sigma \in \{a, b, c, d, \varepsilon\} \\
& q_4(c_{2,4}(x_1, x_2, x_3), y_1, y_2, y_3, y_4) \longrightarrow \\
& \quad q_2(x_1, q_4(x_2, y_1, y_2, y_3, y_4), q_4(x_3, y_1, y_2, y_3, y_4)) \\
& \quad \quad q_2(\bullet', y_1, y_2) \longrightarrow \bullet(y_1, y_2)
\end{aligned}$$

As one can see, the only remaining tree forming symbol which remains on the right hand sides is the concatenation \bullet . So, we are indeed back in our “old” alphabet Σ . The parameters serve just as memory slots to pass the necessary information for undoing the projections and explicit compositions further down into the tree.

From the preceding motivating discussion and the display of the rules in (9) it should be obvious that the states of the MTT do not play any role beyond requiring the right number of arguments. The sort distinctions that are required for both the input and parameter variables can be handled by adding an appropriate look-ahead component that serves to mirror the effect of the tree automaton which specifies the set of intended input trees.

Applying this MTT to the tree in Figure 7 yields the final tree from the derivation displayed in Figure 1. To get the reader started, let us consider the first rule in (9) beginning the transduction on the root of the tree displayed in Figure 7. We start in state q_0 and our root is indeed labeled with $c_{4,0}$. Then we continue in state q_4 with its leftmost daughter and pass as parameters the results of computing q_0 of the other daughters. Since in this case they are elements from $\tilde{\Sigma}_0^L$, we can simply use the appropriate constants from Σ in further computations. The rest of the computation leading to the final result is straightforward and left as an exercise.

6 Conclusion

We have shown in the paper how to account for cross-serial dependencies by coupling a logical domain specification followed by a logically definable transduction and a bottom-up finite-state tree automaton with a tree transformation induced by a macro tree transducer. The result is, of course, not restricted to cross-serial dependencies. Any type of structural relationship that is amenable to a formal analysis by means of CFTGs can be described according to the same operational or logical procedure. The original context-free tree language is first translated into its explicit presentation. A corresponding tree automaton/closed MSO formula then isolates the explicit tree family within the realm of all possible finite trees on the LIFTed signature. The MTT/MSO transduction finally serves to reestablish the intended structural relations.

In the wake of the celebrated result of Peters and Ritchie (1973) on the generative strength of Transformational Grammars a great number of research activities were inspired by the so-called *universal base hypothesis*. One version of this hypothesis can be paraphrased as claiming that there exists a fixed grammar G that plays the rôle of the base component of a Transformational Grammar of any natural language. Adapting this methodological point to our result, it can be stated as follows: Empirical linguistic data that can be accommodated within the framework of CFTGs are amenable to a regular analysis followed by a fixed universal transduction.

Comparing this statement of the result of the paper with the characterization of context-free graph languages by Engelfriet and van Oostrom (1996)

mentioned in the introduction, we want to stress the point that our regular description of context-free tree languages does not provide a characterization of this language family in the technical understanding of an equivalence between context-free tree languages and languages defined by a regular tree language/closed MSO formula and a macro tree transducer/MSO transduction. For a recent result on the equivalence between regular tree languages followed by an MSO definable tree transduction and the tree languages generated by context-free graph grammars see Engelfriet and Maneth (1999).

One drawback of the approach, namely that there is no principled connection between CFTGs and a linguistic formalism which handles the cross-serial dependencies is addressed in another paper. Using the result from Michaelis (1999), a similar technique as the one we have presented in this paper has been applied to code minimalist grammars (MGs) in the sense of Stabler (1997):¹⁴ First, MGs are translated into multiple context-free grammars, and in addition into a restricted form of attribute grammars (cf. Michaelis et al. (2000c)). Multiple context-free grammars can be viewed as Lawvere theories such that we get, again, lifted structures which can be recognized by RTGs/tree automata/MSO formulas. Finally, these lifted structures can be transduced into the intended structures with a variant of the MSO/MTT technique used here (Michaelis et al., 2000a,c). Thus we get another two step approach showing a direct connection between MGs and the account outlined in the present paper.

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¹⁴cf. fn. 6

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